FEATURES

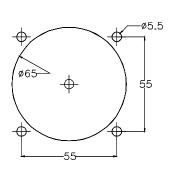
The JHM joystick controller has been designed for use in mobile and industrial field applications. The use of the hall effect sensor, which eliminates any contact between moving electrical parts, improves overall resolution, precision and life. A complete line of built-in electronic drivers, generating on-off, proportional and CANbus control signals, guarantees the highest controllability of any type of electrohydraulic system.

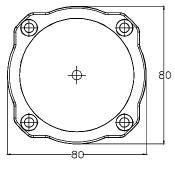
When coupled with an ergonomic multi-function handle of the MS range, up to 5 proportional axes and 9 on-off push buttons can be integrated in the same joystick.

MECHANICAL SPECIFICATIONS	
Main body material:	aluminium
Boot material:	EPDM - UV proof
Lever deflection angle:	±22° ±1° (15° On Request)
Electrical angle:	±22° ±1°
Operating temperature range:	-25°C / +80°C
Protection class (above panel):	up to IP 67, depending on grip
Life:	> 5 million cycles

ELECTRICAL SPECIFICATIONS	
Sensor:	hall effect contactless technology
Supply voltage:	ANL version = 5 VDC ±5%
	other versions = 8÷32 VDC
Current consumption @ rest:	25 mA (sensor only)
Connector type:	Deutsch DT04-12P
	other types available on request
Output signal configuration:	see next pages for all versions

PANEL CUT-OUT AND MOUNTING





AVAILABLE JOYSTICK MOVEMENTS

Option L2S Option L4C Option L4D

Single axis control / Bidirectional Cross axis control / Bidirectional Multi axis control / Bidirectional



JHM ORDERING INFORMATION: see page JK22

ANL & ANH VERSION	
Basic version	
Current consumption @ rest:	< 25 mA (sensor only)
Supply voltage:	ANL version = 5 VDC ±5%
	ANH version = 8÷32 VDC
Signal output @ rest:	2.5 VDC ±0.2 V
Output signal range:	0.5 ÷ 4.5 V ±0.2 V (see graph)
Rated output current:	1 mA
Protections (ANH version):	overvoltage and reversed polarity

AVS VERSIONS

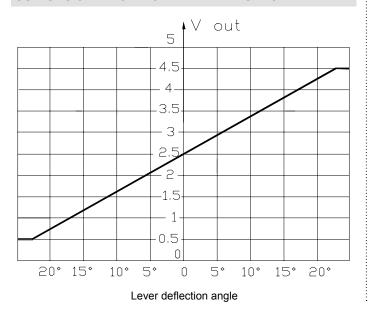
Center tap output signal with digital directional signals

Current consumption @ rest:	< 150 mA (without external load)
Supply voltage (Vin):	8÷32 VDC
Signal output @ rest:	0 V
Output signal range:	0÷5 V ±0.2 V (see graph)
Rated output current:	1 mA

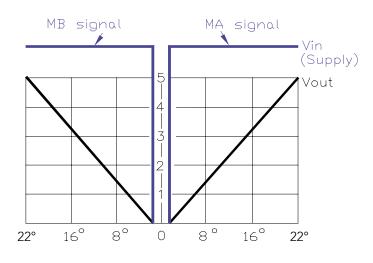
(MA and MB signals on graph)

Digital directional outputs on both axes:	0 / Vin (0.7 A max)
Digital directional outputs switching angle:	between 2° and 5°

OUTPUT SIGNAL CONTROL CHARACTERISTICS



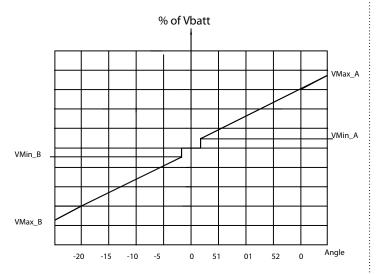
OUTPUT SIGNAL CONTROL CHARACTERISTICS



Lever deflection angle

MLT VERSION Adjustable output signal for closed loop proportional actuators Supply voltage: 8÷32 VDC Current consumption @ rest: 250 mA Analog outputs: linear signal (adjustable) Output signal range: 0.5÷4.5 V 0.9÷4.1 V 2.0÷6.0 V Rated output current: 15 mA Power digital outputs: 4 (0.7 A) Adjustments: via RS232 serial line

OUTPUT SIGNAL CONTROL CURVE



ADJUSTABLE PARAMETERS

The following parameters are adjustable via RS232 serial line by means of a specific calibration and configuration tool.

By use of the configuration window:

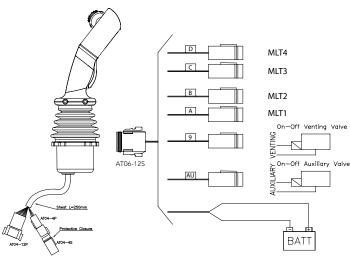
- · Operation mode.
- · Deadman push button enable.
- Joystick functions: axes reverse and enable, virtual cross movement.
- · Assignement for on-off auxiliary outputs.

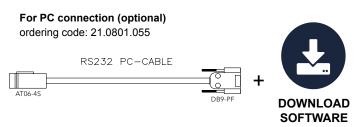
By use of the calibration window:

• Operating parameters: Vmin, Vmax, Ramp up, Ramp down.

APPLICATION EXAMPLE

Shown with MS grip







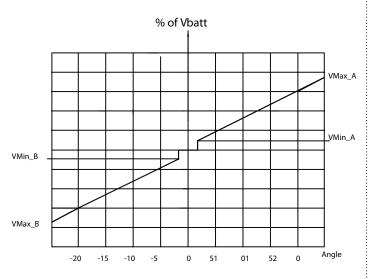
WARNING: the specifications/application data shown in our catalogs and data sheets are intended only as a general guide for the product described (herein). Any specific application should not be undertaken without independent study, evaluation, and testing for suitability.

RTM VERSION

Ratiometric adjustable output signal for closed loop proportional actuators

· · · · ·	
Supply voltage:	8÷32 VDC
Current consumption @ rest:	250 mA
Analog outputs:	5
Output signal range:	linear signal (adjustable)
	25÷50÷75% of Vbatt
	10÷50÷90% of Vbatt
Rated output current:	15 mA
Power digital outputs:	4 (0.7 A)
Adjustments:	via RS232 serial line

OUTPUT SIGNAL CONTROL CURVE



ADJUSTABLE PARAMETERS

The following parameters are adjustable via RS232 serial line by means of a specific calibration and configuration tool.

By use of the configuration window:

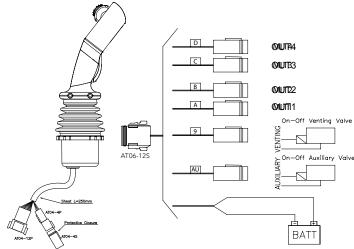
- · Operation mode.
- · Deadman push button enable.
- Joystick functions: axes reverse and enable, virtual cross movement.
- · Output assignement on-off auxiliary valves.

By use of the calibration window:

• Operating parameters: Vmin, Vmax, Ramp up, Ramp down.

APPLICATION EXAMPLE

Shown with MS grip



For PC connection (optional) ordering code: 21.0801.055 RS232 PC-CABLE AT06-4S DB9-PF DOWNLOAD



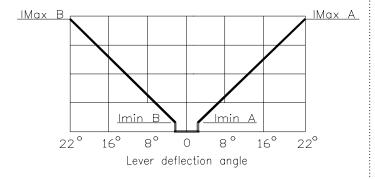
SOFTWARE

PWM VERSION	
2 PWM output channels	
Supply voltage:	8÷32 VDC
Current consumption @ rest:	250 mA
PWM output:	2 x dual proportional solenoid valves
Current output range (PWM):	100 to 1600 mA
	(3 A available on request)
Dither frequency:	60 to 250 Hz (100 Hz factory preset)
Adjustable ramp time:	0.05 to 5 s
Power digital outputs:	2 (3.5 A)
Adjustments:	via PC, RS232 serial line connection,
	using the Tecnord calibration and
	configuration tool (see picture below)

Notes:

- 1) 3rd axis available using FPR-PWM roller switch Imax = 1.5 A
- 2) the base height is 60 mm instead of the standard 46 mm

OUTPUT SIGNAL CONTROL CURVE



ADJUSTABLE PARAMETERS

The following parameters are adjustable via RS232 serial line by means of the calibration/configuration tool.

By use of the configuration window:

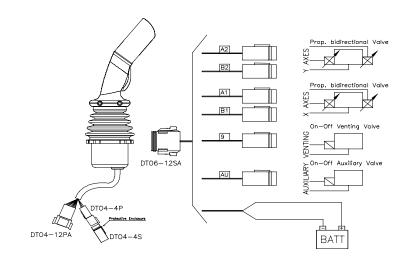
- Operation mode.
- Deadman push button enable.
- Joystick functions: axes reverse, virtual cross movement.
- Current setpoint selection (for 360° movement only).
- · Output assignement on-off auxiliary valves.
- Digital directional output signals on both axes (N.O. or N.C. mode)

By use of the calibration window:

Operating parameters: Imin, Imax, Ramp up and Ramp down times.

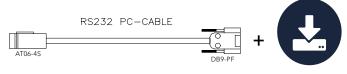
APPLICATION EXAMPLE

Shown with MS grip

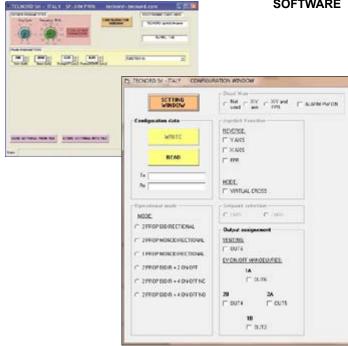


For PC connection (optional)

ordering code: 21.0801.055





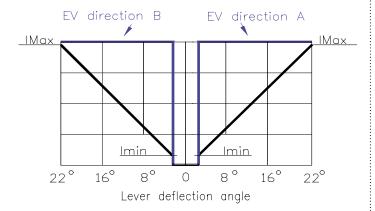


TCN VERSION (special configuration of PWM version)

1 PWM output in combination with up to 5 on-off outputs

Supply voltage:	8÷32 VDC
Current consumption @ rest:	< 250 mA
PWM output:	1 x single proportional solenoid valves
Current output range (PWM):	100 to 1600 mA (3 A available on request)
Dither frequency:	60 to 250 Hz (100 Hz factory preset)
Adjustable ramp time:	0.05 to 5 s
Power digital outputs:	5 (3.5 A)
Adjustments:	via PC, RS232 serial line connection,
	using the Tecnord calibration and
	configuration tool (see picture below)

OUTPUT SIGNAL CONTROL CURVE



Imin and digital outputs activation: between 2° and 5°

ADJUSTABLE PARAMETERS

The following parameters are adjustable via RS232 serial line by means of a specific calibration and configuration tool.

By use of the configuration window:

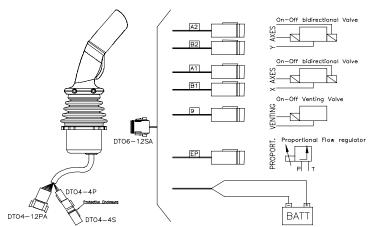
- · Operation mode.
- · Deadman push button enable.
- · Joystick functions: axes reverse, virtual cross movement.
- Current setpoint selection (for 360° movement only).
- · Output assignement on-off auxiliary valves.

By use of the calibration window:

· Operating parameters: Imin, Imax, Ramps.

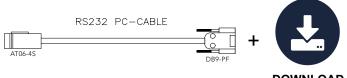
APPLICATION EXAMPLE

Shown with MS grip

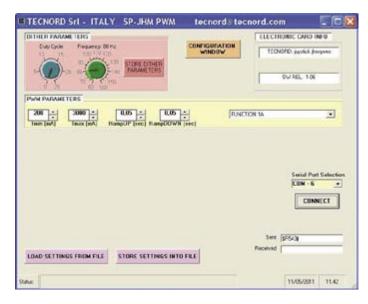


For PC connection (optional)

ordering code: 21.0801.055



DOWNLOAD SOFTWARE



CANBUS VERSION	
Supply voltage:	8÷32 VDC
Current consumption @ rest:	< 250 mA
Physical layer:	ISO 11898, 250 Kbit/s
Protocol:	J1939/ CANopen
Connector type:	Deutsch DT04-4P

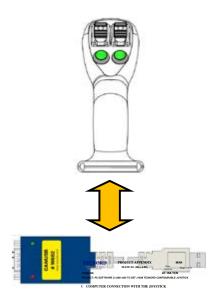
With CANbus link, following signals can be managed on the multifunctional grip:

- 4 digital outputs 0.7A (LEDs, detent coils, buzzers, etc).
- 6 analog voltage input 0-5 V (proportional rollers and mini-joysticks).
- 6 digital inputs (push buttons, toggles, etc).

CONNECTIONS

Deutsch DT04-4P

- 1 +V (POWER SUPPLY)
- 2 CAN L
- 3 CAN H
- 4 -V (POWER SUPPLY GND)



ADJUSTABLE PARAMETERS

The following parameters are adjustable via CAN:

For CANopen version

Node ID

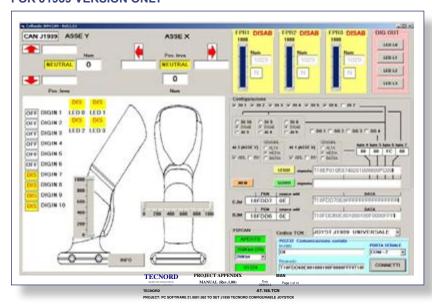
For J1939 version

Node ID

In addition, with the specific "Calibration and Configuration PC Tool" and the CAN/USB hardware interface device (see picture below) is possible:

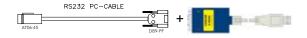
- · Read joystick configuration
- Adjiust X, Y axles sensibility and direction
- Enable /disable digital or analog inputs and digital outputs

FOR J1939 VERSION ONLY



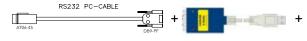
CANOPEN VERSION ONLY

ordering code: 21.0801.083



J1939 VERSION ONLY

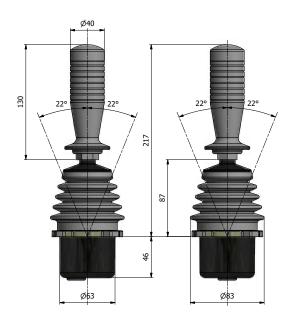
ordering code: 21.0801.062



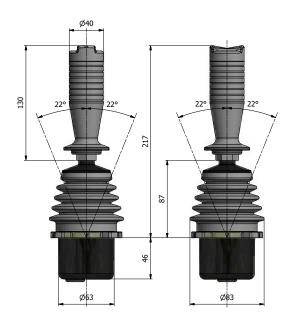


SOFTWARE

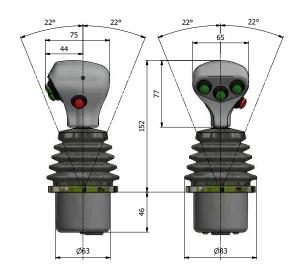
JHM joystick with grips - configuration examples with overall dimensions



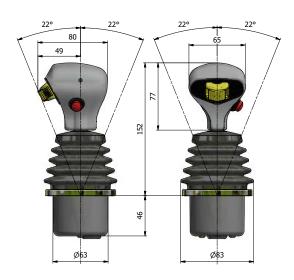
JHM base with IC handle
Complete code: JHM-L4D/ANH-IC-0000



JHM base with IC handle Complete code: JHM-L4D/ANH-IC-0200



JHM base with IE type handle Complete code: **JHM-L4D/ANH-IE-A3P9-0000**



JHM base with IE type handle
Complete code: JHM-L4D/ANH-IE-A1FPR-0000

JHM joystick with grips - configuration examples with overall dimensions



JHM base with MS type handle Complete code: **JHM-L4D/ANH-MS-A6P9-R3P9**



JHM base with MS type handle
Complete code: JHM-L4D/ANH-MS-A2P9-2FPR-R1P9



JHM base with MG type handle Complete code: **JHM-L4D/ANH-MG-A4P9-R1P9**



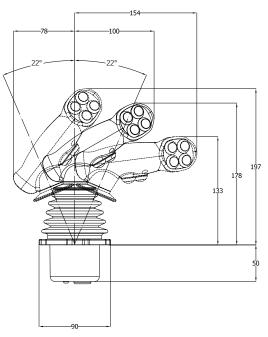
JHM base with MG type handle
Complete code: JHM-L4D/ANH-MG-A2P9-1FPR-0000

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JHM joystick with HL - HR grips - configuration examples with overall dimensions



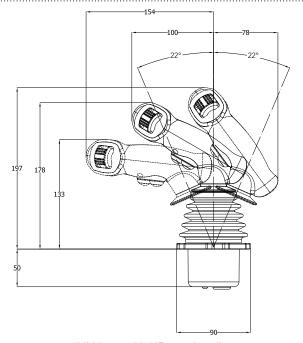
JHM base with HL type handle Complete code: **JHM-L4D/ANH-HL-01FPR-2P9-R000**



JHM base with HL type handle Complete code: **JHM-L4D/ANH-HL-04P9-2P9-R000**



JHM base with HR type handle
Complete code: JHM-L4C/NN-HR-04P9-2P9-R1FPR



JHM base with HR type handle Complete code: **JHM-L4C/NN-HR-0FPR-2P9-R000**